

DETROIT DIESEL



Next Generation Diesel Engine Control

Detroit Diesel Corporation

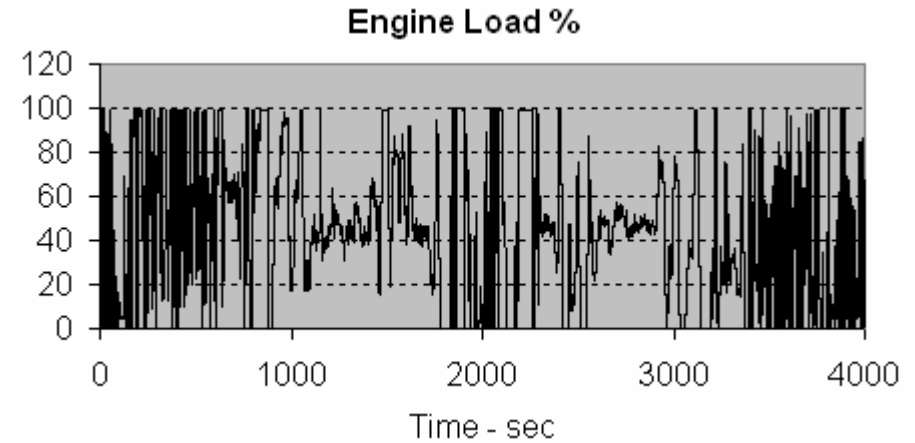
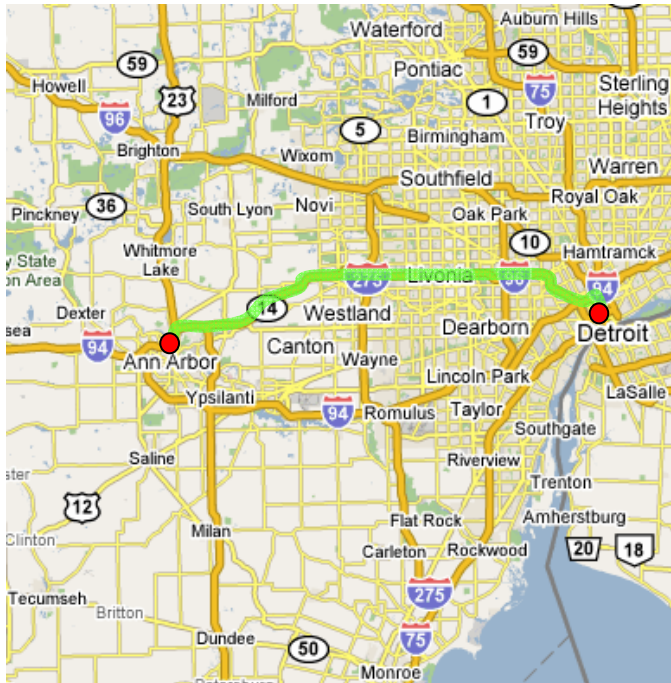
M. Allain, C. Savonen, Y. Kalish, H. Zhang



- **Engine Control Requirements**
- **Inverted Models For Controls**
- **Results**
- **Limitations**



Steady-State ?



Transient Engine Control Makes
Advanced Combustion Techniques
Possible Over-the-road



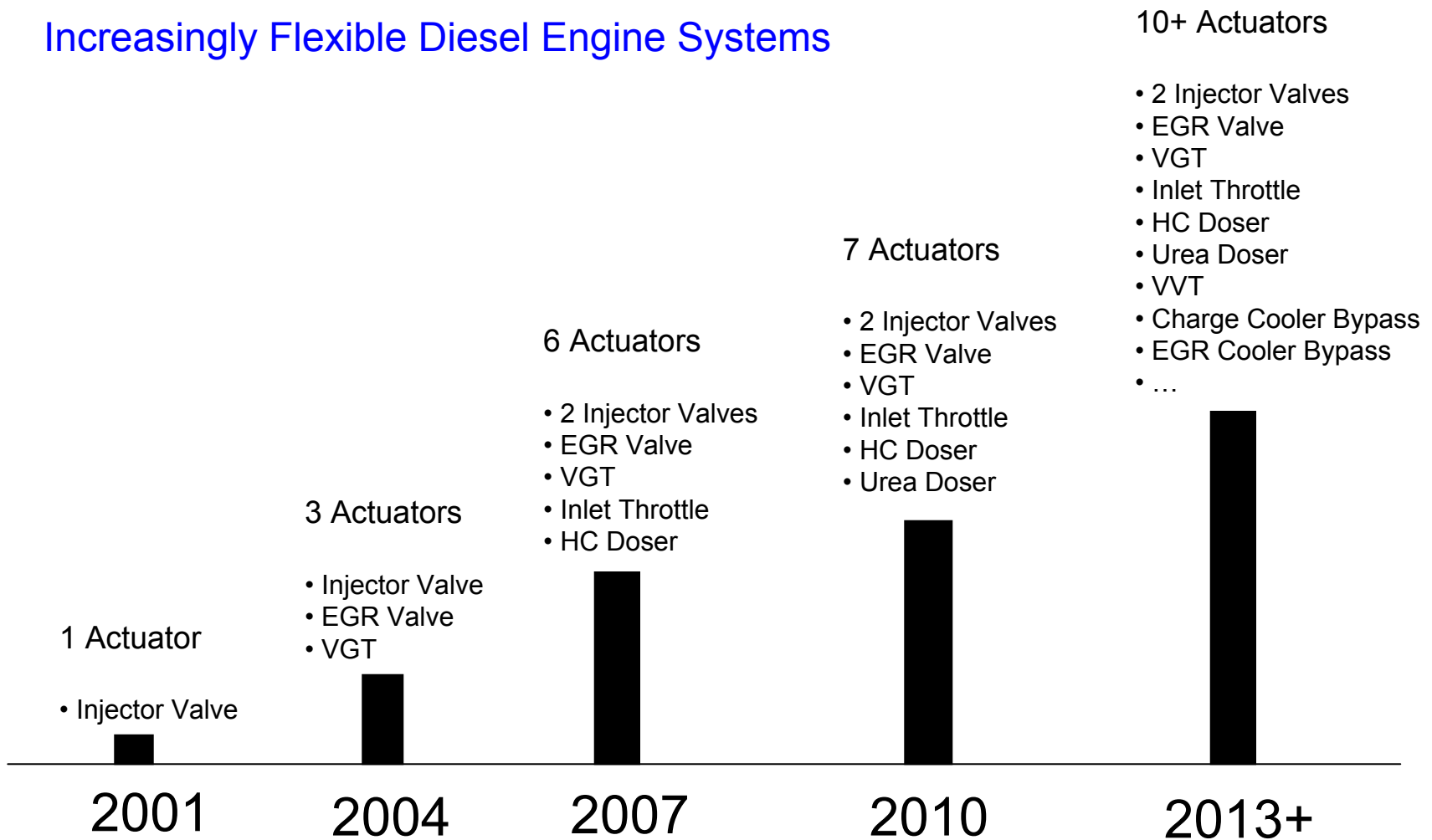


- **Flawless Steady-State Stability**
- **Fast Transient Response**
- **Reduced Emission Variability**
- **Increased Diagnostic Capability**
- **Integration of Additional Control Variables**

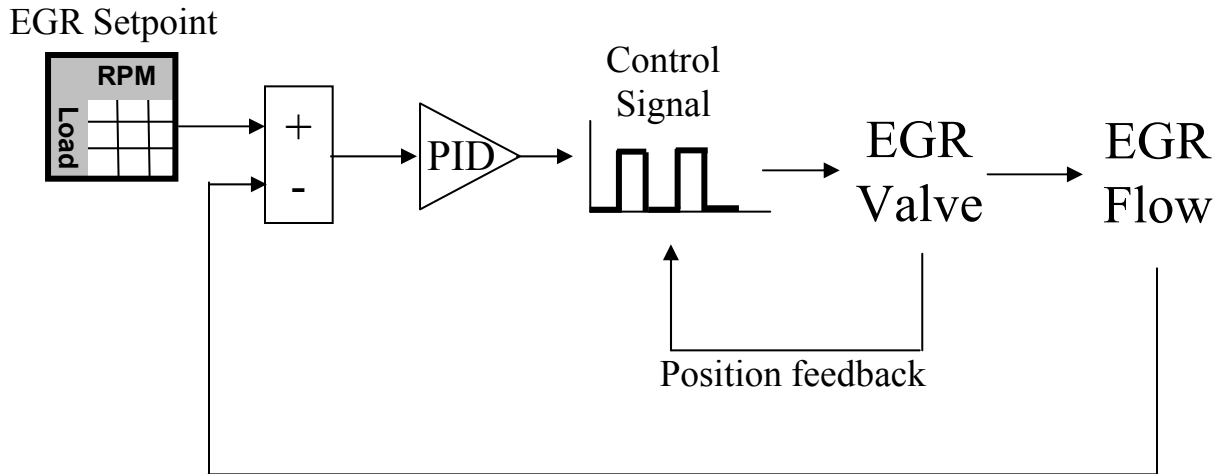
Multiplication Of Control Variables



Increasingly Flexible Diesel Engine Systems



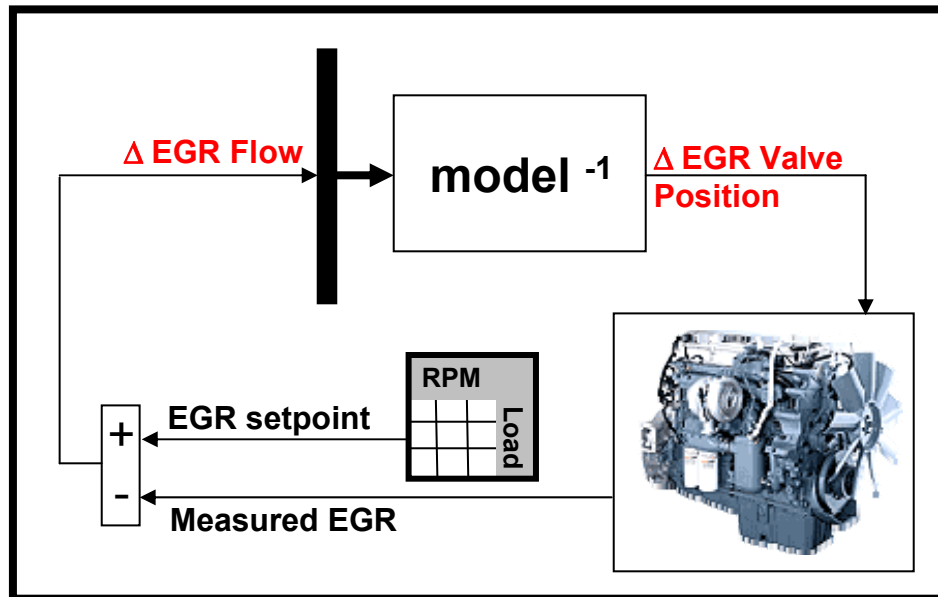
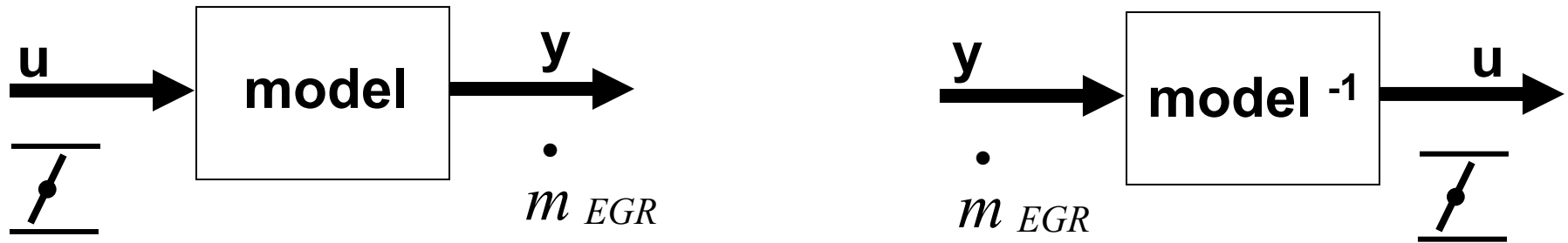
Traditional Engine Control



Next Step: Model-Based Engine Control



Next Step – Inverted Control Model

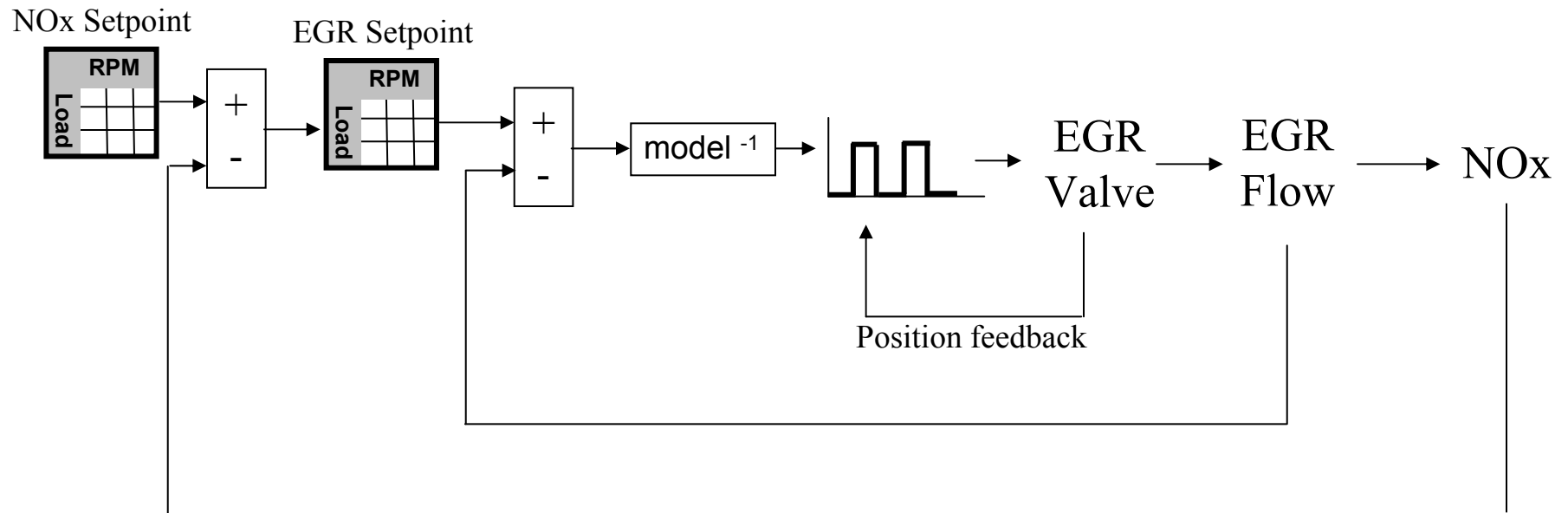


Model-Based Control System

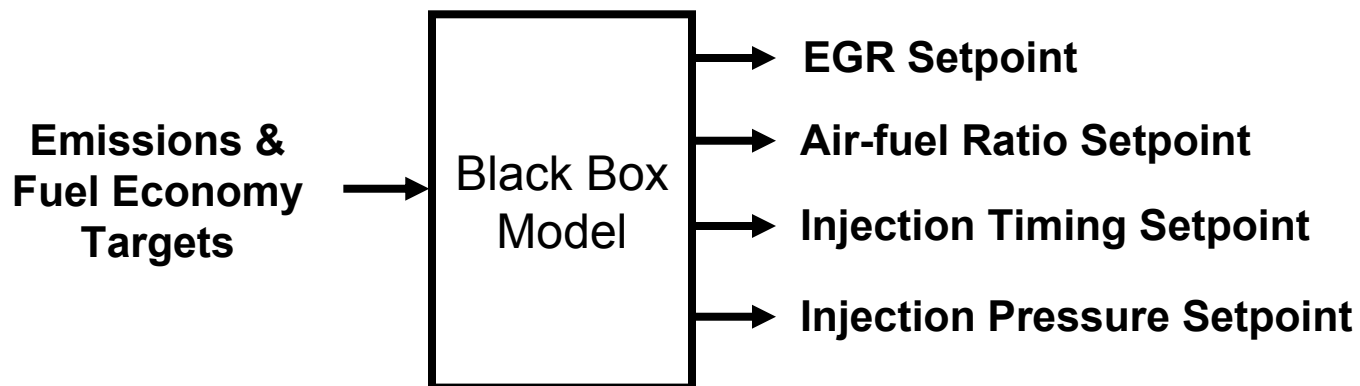
Significant Improvements
Obtained in Stability &
Response Time



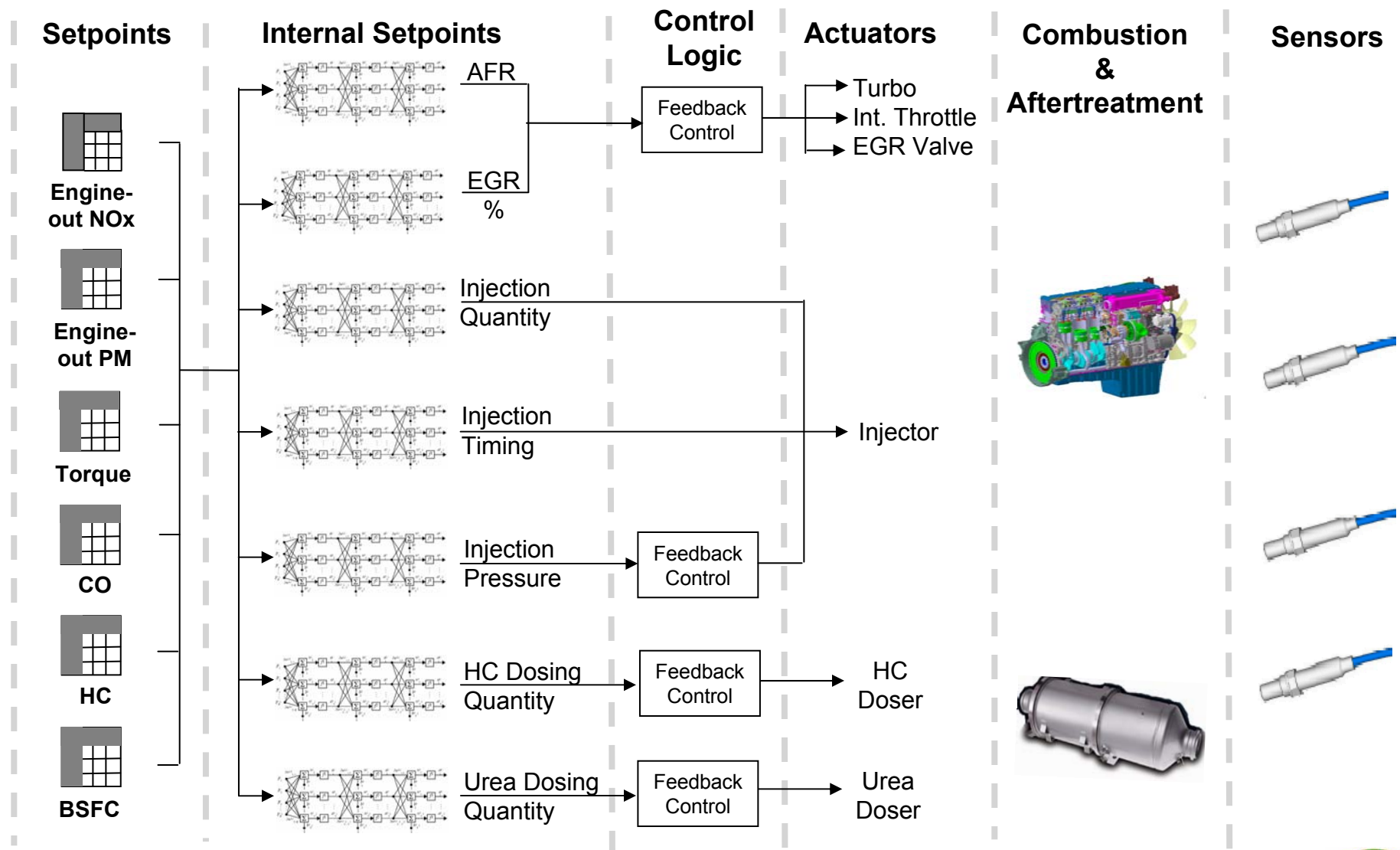
Can We Take It Further ?

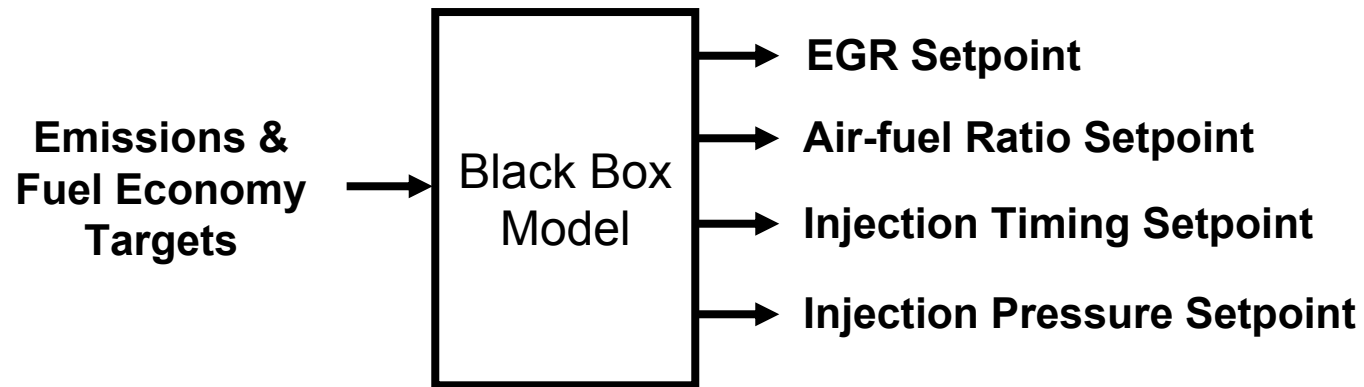


Can we build a model, which calculates optimum setpoints in real-time ?



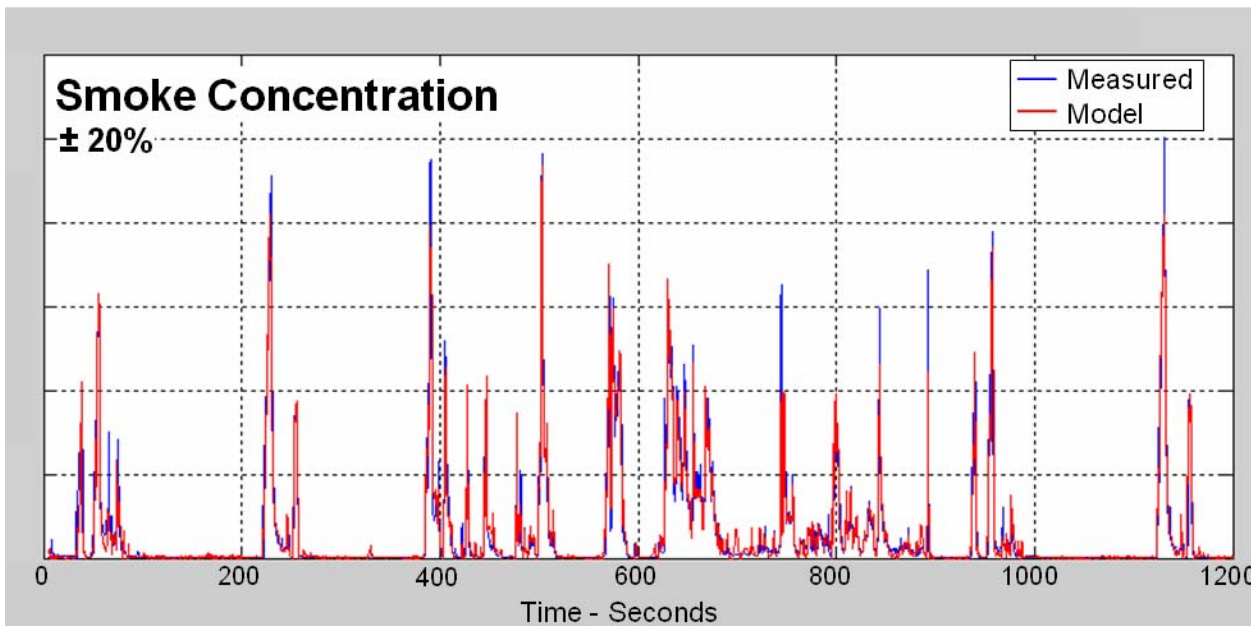
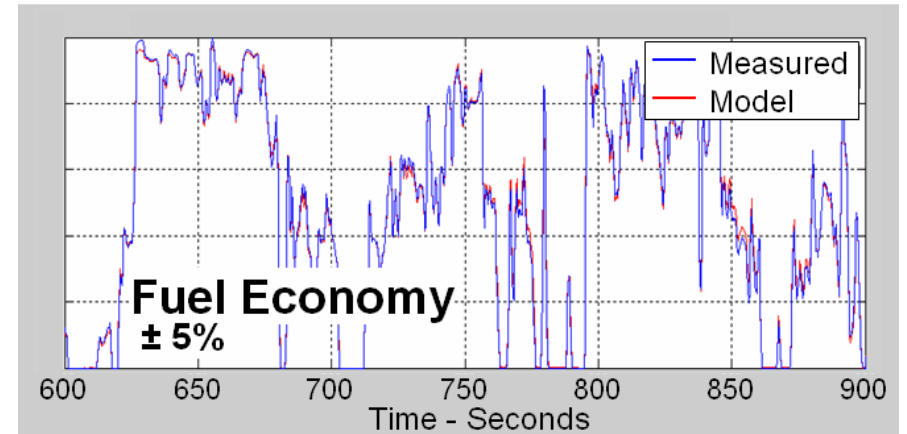
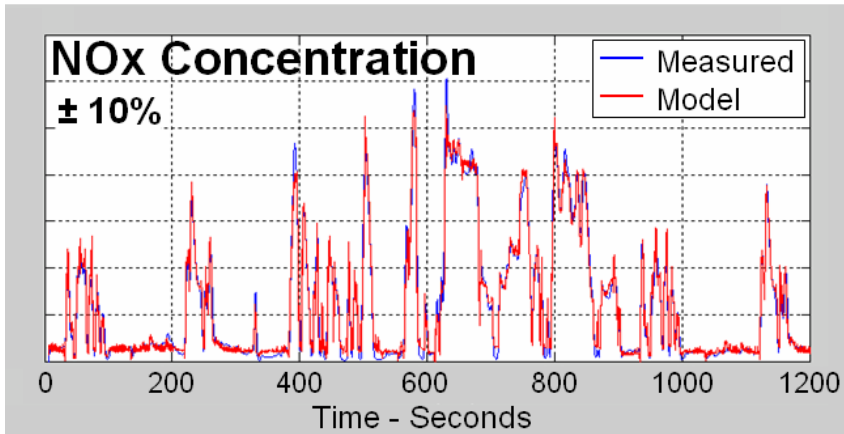
Calibration Layers





- Are Forward Models Accurate ?
- How Accurate Must The Inverted Models Be ?

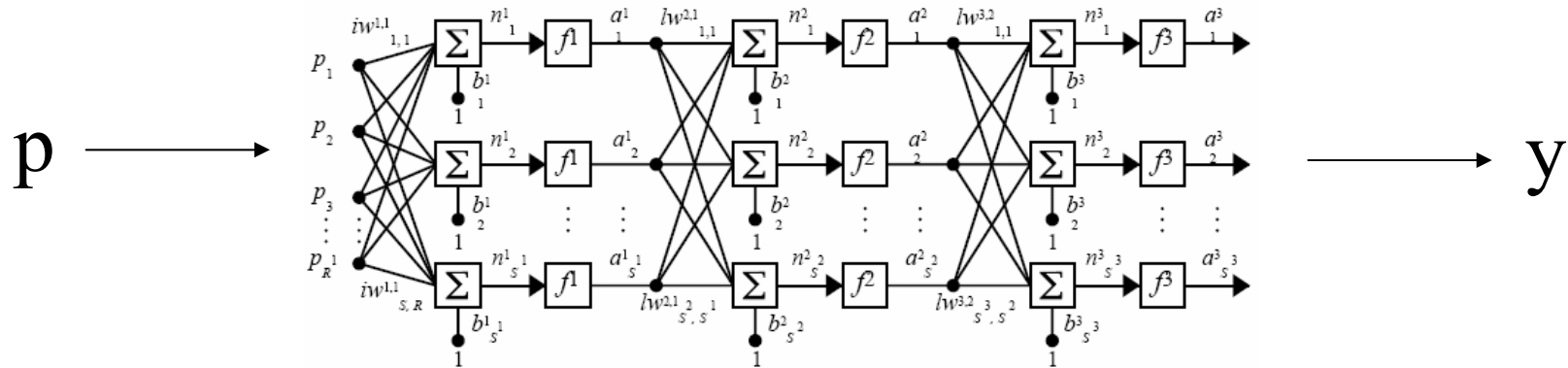
Neural Network Model Evaluation



PM Model Is More Challenging:

- Additional Inputs
- Time History of Inputs



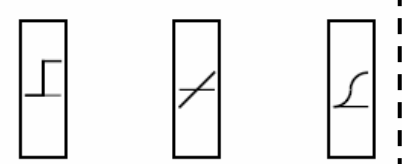


- Fixed Pre-defined Structure
- Training With Existing Input-Output Data

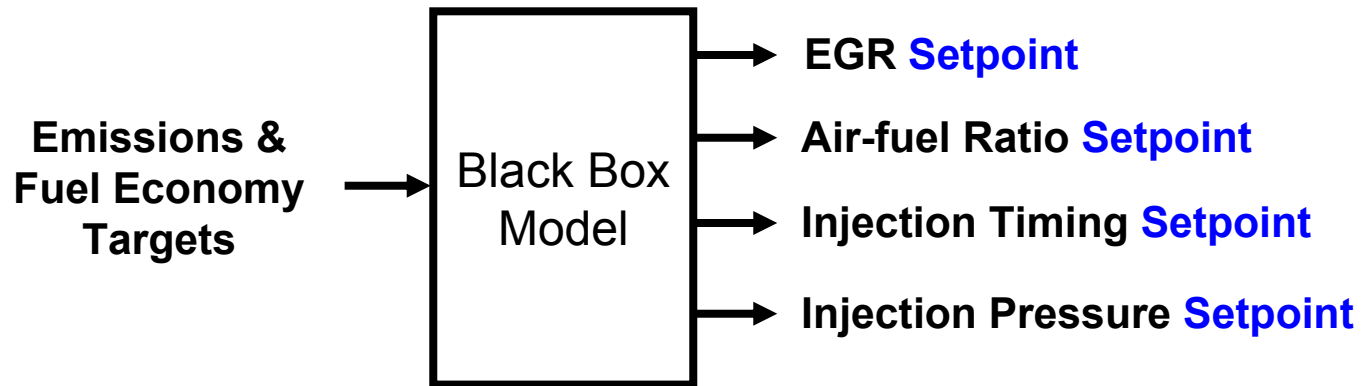
Weights Biases

$$y = f(Wp + b)$$

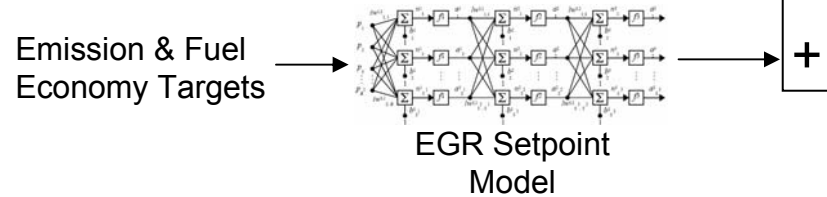
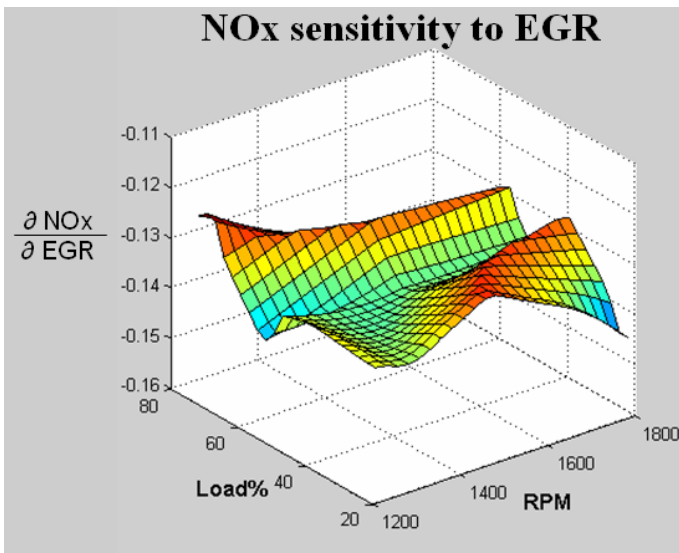
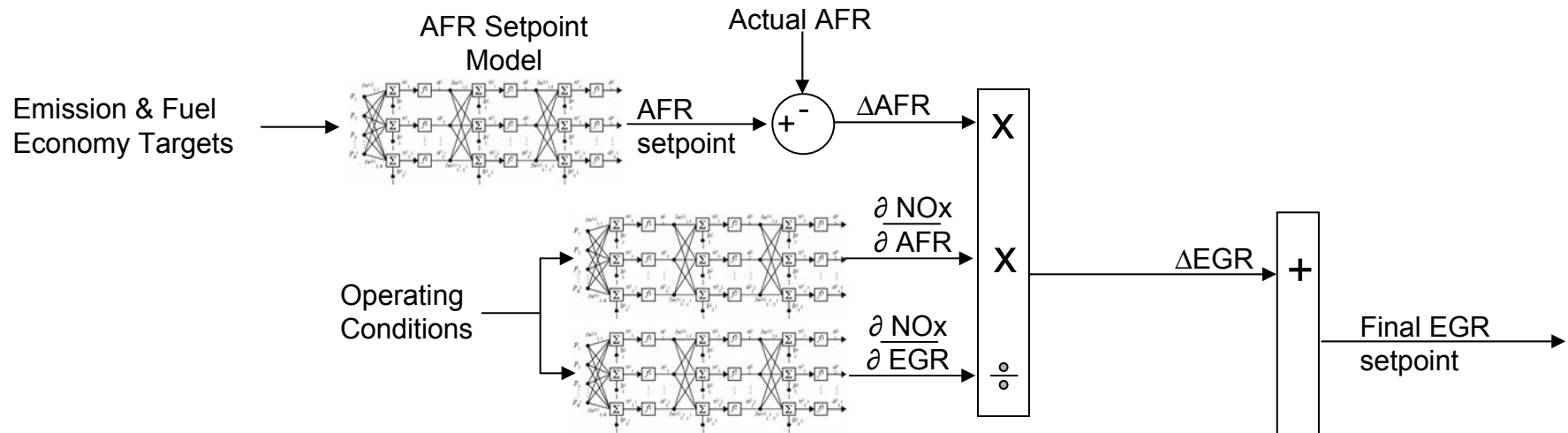
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Problem: Setpoint vs. Actual !



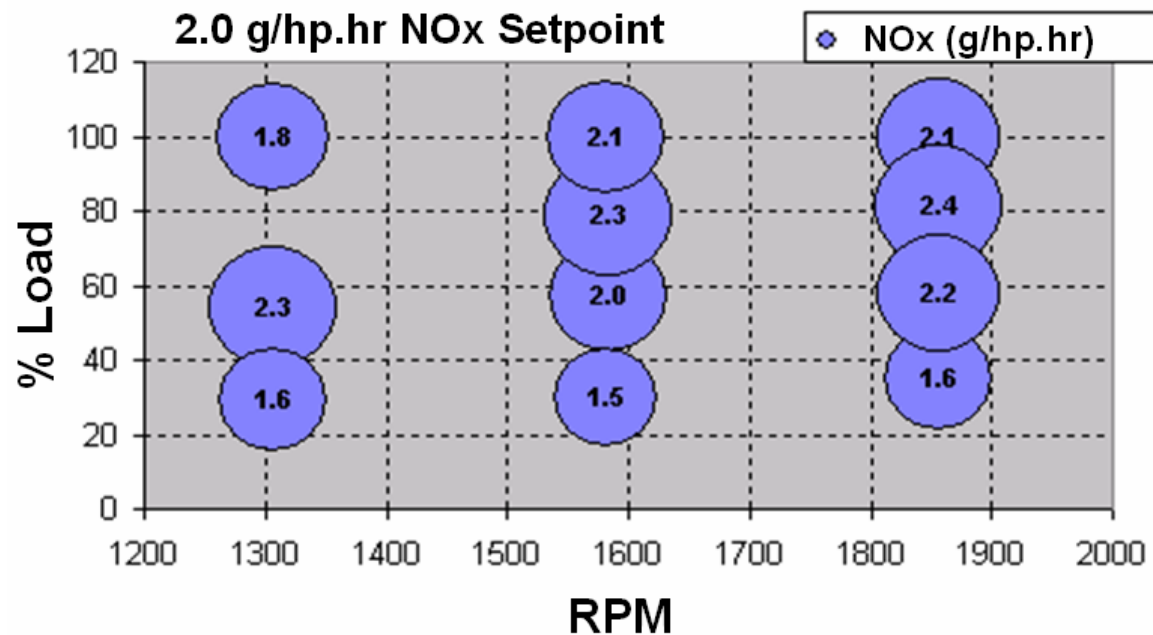
Intermediate Solution - Dynamic Compensation



Take Advantage of Fast-responding Engine Systems



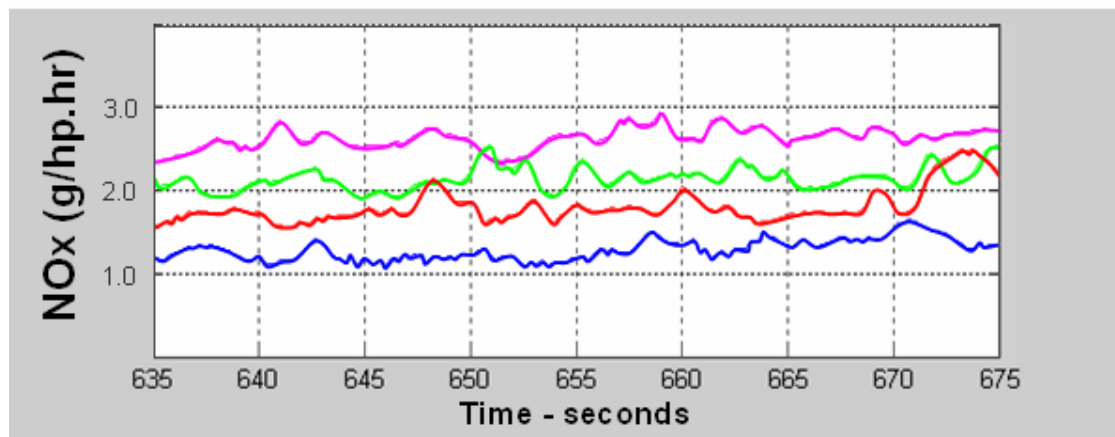
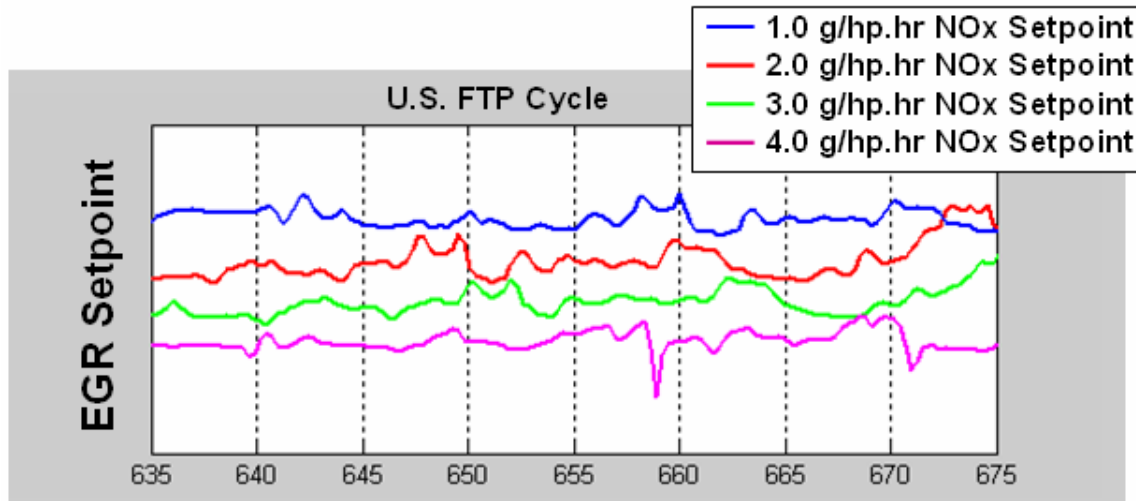
Steady-state Results



Objective:

- Dial-in the Requested NOx Level
- Have the Controller Adjust the Engine Setpoints to Meet the Emission Targets

Transient Results



Dynamically Calculating
The Optimum Setpoints

Model Inaccuracy Can Be
Compensated
By Adjusting the Emission
Setpoints

- Large Amount Of Transient Data Required
- Over-the-road Application
- Hardware Variability (engine-to-engine)
- Increased Computing Power Requirement



- Developing Transient Engine Models For Real-time Use
- Models Were Inverted For Control Application
- Results Obtained To Date Indicate Strong Potential
- Major Challenge Is Applicability To Varying Ambient Conditions
 - Possible On-board Model Adaptation
- Next Steps Include The Application To Standard ECU



Acknowledgements



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