

A New Class of Switched Reluctance Motors Without Permanent Magnets

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Project ID: APE020

Overview

Timeline

- Start: FY09
- Finish: FY11
- 50% Complete

Budget

- Total project funding
 - DOE: 100%
- Funding Received in FY09: \$569K
- Funding Received for FY10: \$447K

Barriers

- Barriers
 - Maintaining power density
 - Minimizing flux leakage
 - Reducing acoustic noise and torque ripple
- Targets
 - Motor power density:
 - 5 kW/L (2015 target)
 - Motor specific power:
 - 1.3 kW/kg (2015 target)
 - Motor cost:
 - Between \$7/kW (2015 target) and \$4.7/kW (2020 target)

Partners

- University of Tennessee
- MotorSolver LLC

Objectives

- The purpose of this multi-year project is to design, develop, build, and test a novel SRM traction drive that has a higher power density and significantly lower torque ripple and acoustic noise than conventional SRMs while maintaining the simplicity, low cost, and power density of the conventional SR machine
- Explore potential to remove boost converter or reduce battery voltage
- Seek to provide initial quantitative results showing that estimated characteristics of the proposed design reach the following targets:
 - Power density: 5 kW/L (2015 DOE target)
 - Specific power: 1.3 kW/kg (2015 DOE target)
 - Motor cost between \$7/kW and \$4.7/kW (2015 and 2020 targets, respectively)
- FY10 Objectives
 - Develop and refine control scheme
 - Conduct acoustic and structural modeling
 - Perform dynamic simulations
 - Arrive at final optimized design

Milestones

Month/Year	Milestone or Go/No-Go Decision
September 2009	Milestone: Choose preferred design approach and associated preliminary control algorithm
September 2009	Go/No-Go decision: Determine if preferred design approach has the potential to address DOE targets based on preliminary studies
September 2010	Milestone: Parametrically optimize preferred design approach and control scheme
September 2010	Go/No-Go decision: Determine if finalized prototype design has the potential to address DOE targets based on detailed analyses

Approach

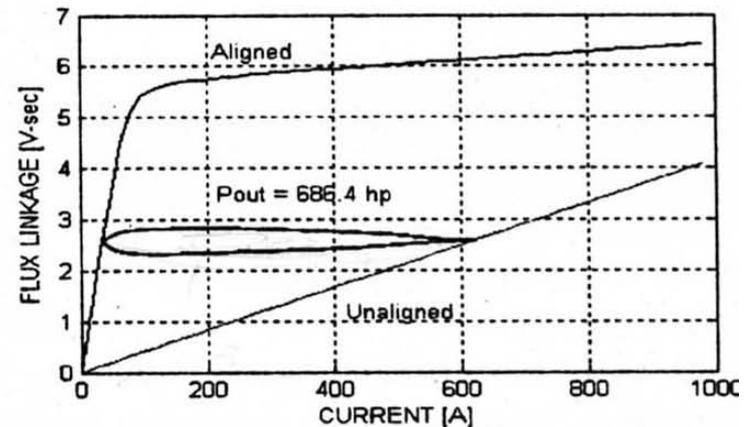
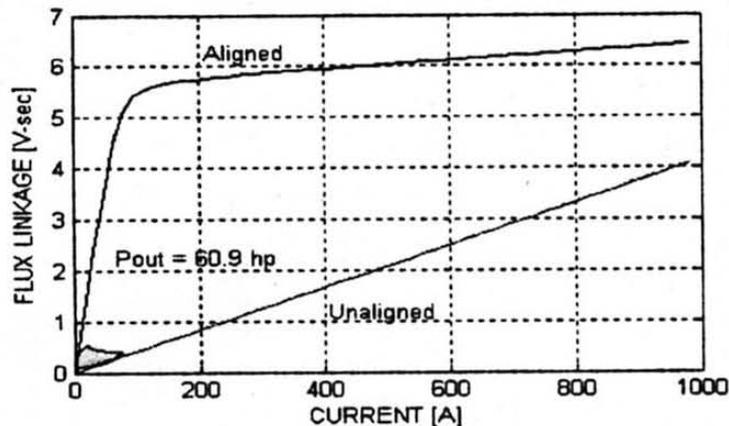
- **Select preferred design approach of novel switched reluctance machine**
 - Analyze basic feasibility of various novel switched reluctance machine designs
 - Conduct finite element analysis (FEA) to obtain motor characteristics
 - Develop preliminary novel control schemes
 - Simulate final design(s) with basic dynamic model
 - Obtain estimated capabilities of torque and power as a function of speed
 - Choose preferred design approach based on preliminary cost assessments, FEA, and dynamic simulation results
- **Perform detailed design and simulation of selected design approach**
 - Conduct structural, thermal, and acoustic noise modeling
 - Adjust design approach as necessary
 - Investigate potential to apply air-gap enhancements
 - Carry out comprehensive dynamic simulations
 - Refine novel control algorithm and investigate potential to apply other novel control techniques
 - Obtain accurate capabilities of torque and power as a function of speed
- **Build and test SR motor prototype and novel control technique**
 - Determine power density, specific power, and cost based on results from dynamometer tests

FY09 Technical Accomplishments (1)

- **Completed FEA design studies of numerous approaches**
 - Feasibility of several unconventional designs verified through extensive FEA simulations with consideration of estimated capabilities
 - Manufacturing and material costs
 - Peak-torque
 - Torque-ripple
 - CPSR (constant power speed ratio)
 - Mass and volume
 - Most plausible design approach selected based on terms of cost, complexity, performance, torque ripple, and acoustic noise
- **Two dynamic three-phase electromagnetic simulators developed (with consideration of mutual coupling)**
 - FEA-based
 - Most accurate
 - Good for design optimization
 - Not good for control optimization
 - Parametric
 - Still accurate
 - Can play role in parameterized optimization
 - Great for control optimization
 - Both FEA and parametric dynamic models are being developed and will have universal capabilities, regardless of the embodiment or motor type (SR, PM, induction, etc)

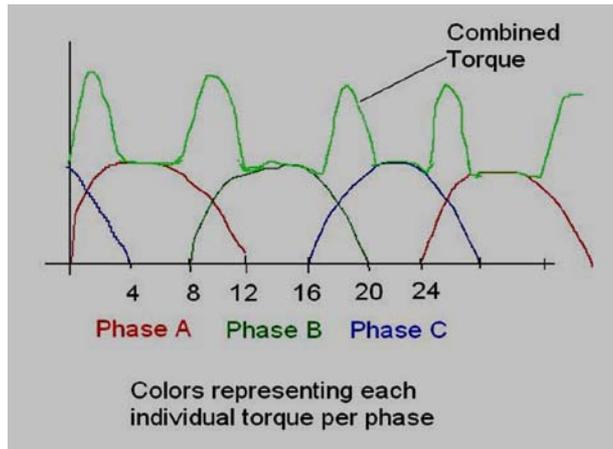
FY09 Technical Accomplishments (2)

- Verified that continuous conduction control can be utilized with preferred design approach
 - Continuous conduction (CC) control consists of a non-zero minimum current, contrary to that of conventional control
 - Much higher power capabilities are available since a higher flux linkage is attained prior to reaching the torque producing region
 - Creates potential to reach power levels up to 2 times that of a conventional control method
- Originated integration of hardware and software solutions

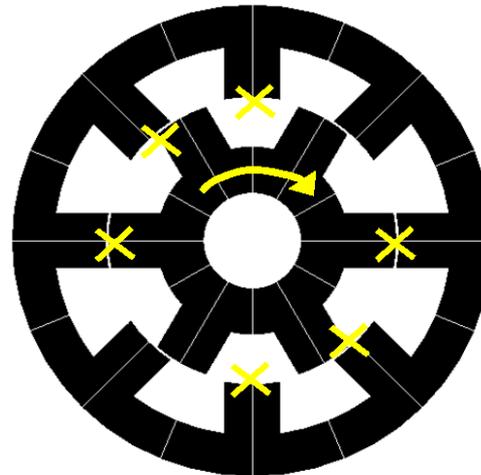


FY10 Technical Accomplishments (1)

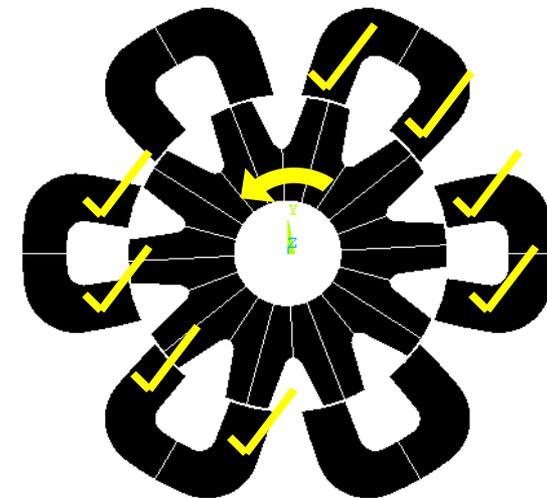
- Novel design and control techniques provide opportunity to significantly reduce torque ripple and acoustic noise
 - Average number of instantaneous active teeth increased
 - Proper control allows increase of utilized air-gap area without sustaining substantial leakage
- No positions associated with “near zero” or “approaching zero” locked rotor torque



Exemplary sketch
of locked rotor
torque profile



Conventional 8/6
(4-phase)



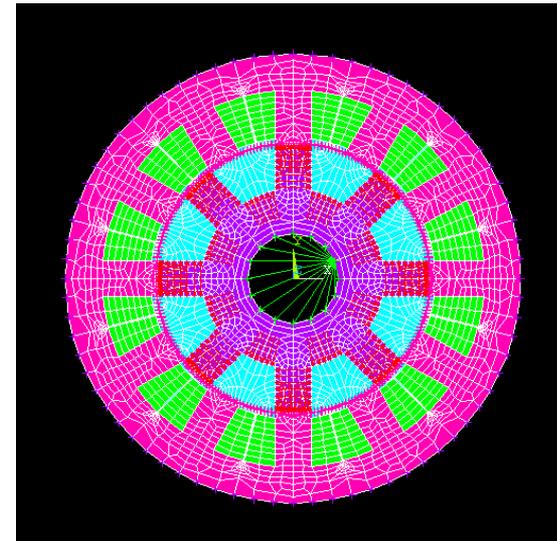
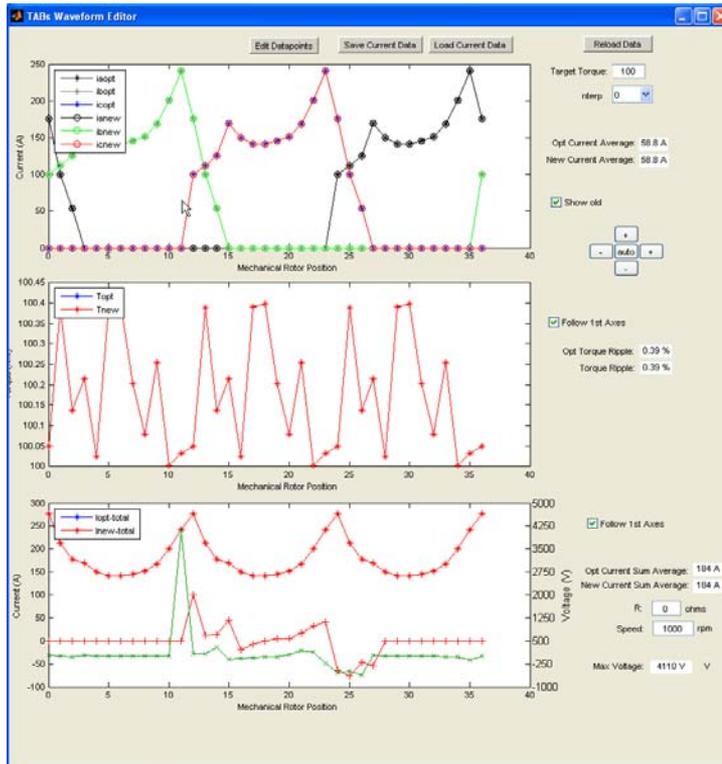
12/10 prior to
optimization

FY10 Technical Accomplishments (2)

- Achieved higher amount of ampere-turns (and thus torque capability) within same volume of a conventional SR
 - Increased winding area
 - Enhanced heat transfer capabilities
 - Improved manufacturability by winding coil prior to assembly
- Established that the design is capable of very high speed operation
 - Same simple rotor design as conventional SR
- Verified the following advantages of using separate stator pieces
 - Reduced modal tendencies of stator
 - Dampening composite could be used to attenuate vibration
 - Could also serve as thermal conductor
 - Noise and vibration can be greatly reduced
 - Further improving upon impact of reduced torque ripple
 - Decreased core/eddy current losses due to short flux paths

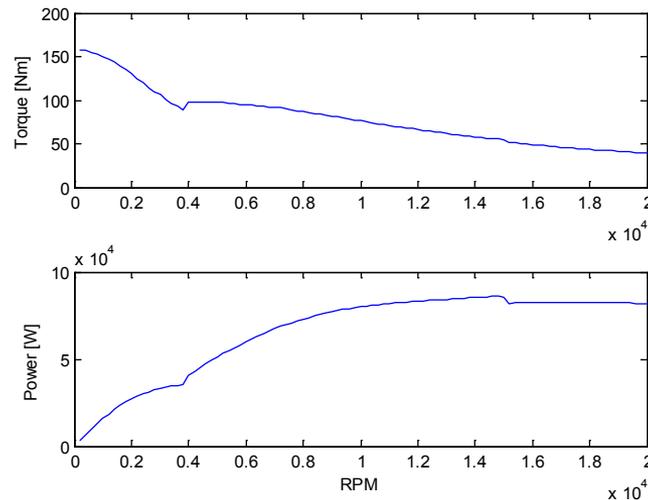
FY10 Technical Accomplishments (3)

- EMAG, thermal, structural, acoustic FEA capabilities being combined in one package
 - Allows seamless and efficient comprehensive motor design studies
 - Not commercially available



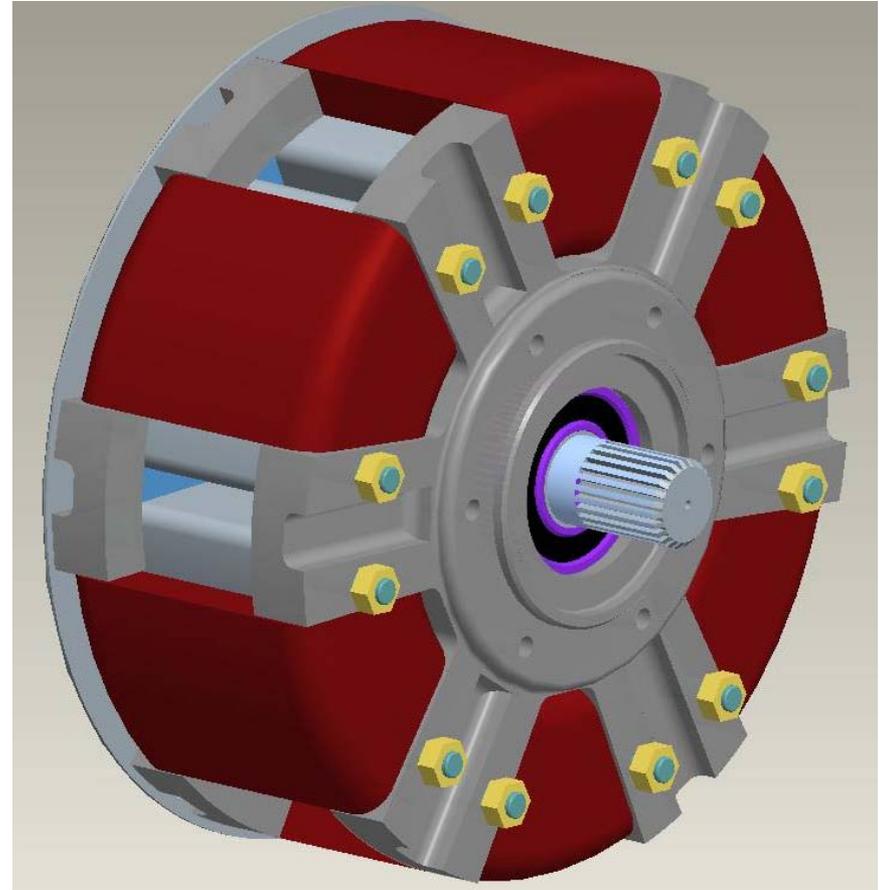
FY10 Technical Accomplishments (4)

- Preliminary non-optimized studies at 100 Nm and 2,000 rpm (20 kW) with less than 1% torque ripple
 - Note: optimization was conducted at this arbitrary point and is not maximum torque or power level
- Detailed dynamic simulations using continuous conduction reveal that a 90 kW power level can be obtained with a preliminary design having dimensions and system parameters (voltage, current, etc) similar that of the Prius
 - Assuming similar mass and volume as Prius motor
 - 5.8 kW/L vs 2015 target of 5 kW/L and 2020 target of 5.7 kW/L
 - 2 kW/kg vs 2015 target of 1.3 kW/kg and 2020 target of 1.6 kW/kg
 - Further design refinements to be made
 - Reduce power level and increase torque capability



FY10 Technical Accomplishments (5)

- Investigating tradeoffs between the use of firm structural support versus malleable dampening material
 - Dampening composite provides great benefit for the reduction of noise/vibration
- Preliminary design efforts have already resulted in feasible design options with consideration of cost, complexity, and manufacturing



Collaborations

- University of Tennessee
 - Provides feedback regarding fundamental machine design principals, assists with the development of modeling tools, and analyzes operational characteristics of operating in continuous conduction
- MotorSolver LLC
 - Provided feedback regarding fundamental machine design principals

Future Work

- FY10
 - Continue development of control algorithm
 - Continue comprehensive dynamic, acoustic, and structural modeling
 - Finalize design

- FY11
 - Incorporate control scheme onto DSP
 - Build and test SR motor prototype and test with novel control technique

Summary

- Design maintains the following conventional switched reluctance motor benefits:
 - Low material and fabrication cost
 - No permanent magnet material
 - Back-emf and demagnetization is not an issue
 - Permits operation at high temperatures
 - Capable of high speeds
 - Robust and reliable
- Improvements upon conventional SR technology
 - Significant reduction of torque ripple and acoustic noise
 - By utilizing greater percentage of air gap than that of a traditional SR motor
 - Less than 5% torque ripple for low and moderate torque and speed operation points
 - Localized flux paths yielding lower core losses
 - Increased winding area → more ampere-turns per motor size